

- ABSTRACT:** The Astroparticle field is actively searching for the origin and the nature of the Ultra-high energy cosmic rays from deep within the Universe as they carry the information from those regions and might also hint on possible new physics. This talk reports on the overall design and the ongoing construction and calibration of DUCK (Detector system of Unusual Cosmic-ray casKades), a new cosmic-rays detector at the Clayton State University campus with ns-level detection resolution. The main scientific importance for the DUCK project will be to contribute to the approach of cosmic ray event analysis using the full waveform and detector response width, and to an independent verification of the detection of the 'unusual' cosmic ray events that were reported by the Horizon-T detector system that may be indicating direction towards the novel physics possibilities.

### Introduction

High Energy Physics (HEP) is a field that has still has many mysteries that need to be solved. An open question is about the origin and composition of the Ultra-high Energy Cosmic Rays (UHECRs). These cosmic rays originate well outside our planet, may be even outside of the galaxy. They are messengers that could help us better understand the universe around us and provide insight into the fundamental building blocks of our universe.

The primary goal of the DUCK system [1] is to detect and verify the existence of unusual cosmic events [2, 3]. Moreover, it can help innovate EAS (Extensive Atmospheric Shower) analysis methods. This poster aims to highlight development and construction of the detector system, instrument calibrations and other activities conducted at Clayton State University.

### 3D Hardware Design

Using OnShape CAD, the PMT Upper Shell (Figure 1), Holder (Figure 3) and Optic Fiber ferule (Figure 4) for Module 1 were designed and 3Dprinted.

Notes taken about "CAD-ing":

- Use Planes to manipulate where objects originate
- Splicing using UltiMaker Cura 5.3 or similar after downloading the .stl file.
- Operating a 3D printer (Figure 2) and troubleshooting problems.
- Use fine mode for stl file, units in mm. Adjust other parameters as needed.

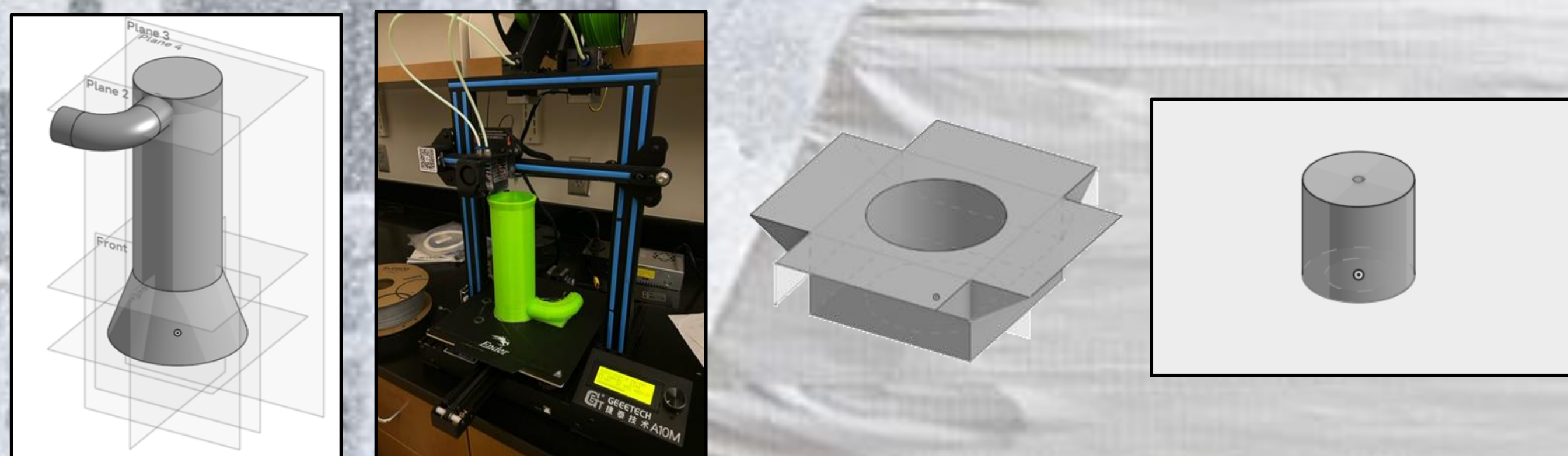


Figure 1. PMT holder shell . Figure 2. PMT holder printing. Figure 3: PMT base holder Figure 4. Optic Fiber ferule for MPPC.

### Project Progress Report

- Modules #1 and #2 has been fully built, and all hardware components are now operational. (Figures 5 and 6)
- Several new hardware additions were designed and implemented, including the PMT holder and mount, as well as PMT cable management. (See 3D hardware design section)
- Two more modules are under construction. (Figure 7)
- Initial calibrations were conducted.



Figure 5. Module #1

Figure 6. Module #2

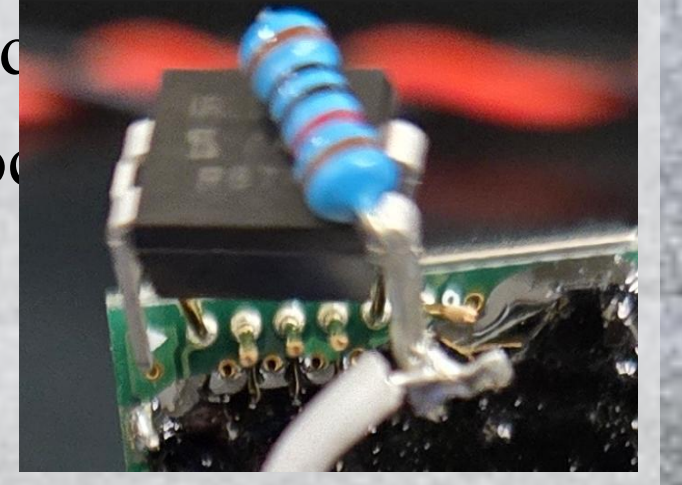
Figure 7. Modules 3 and 4



Figure 8. ADC

Figure 9. Secondary photodetector (MPPC) installation

- Figure 8 is the DT5730 ADC used
- Figure 9 is the Hamamatsu [4] Power supply C11204-01 for the MPPC photosensor. In- 5V, out - <90V, covers MPPC range needed.
- Issues:
- COM-port communication, on power loss – loses last setting, starts with default of 40V – Arduino controller to monitor
- Old protocol, slow speed. Unnecessarily complicated commands
- Needs to be 'reset' when loaded: short NC pin to ground, undoes
- No overload/short protection
- Worst product by Hamamatsu ever?**



- H11284-30 (former R7723) PMT from Hamamatsu is used as primary photosensor (one of the best PMTs arguably)
- Great/robust C9619-01 power supply



### ROOT-based file format

- The data acquisition (DAQ) method is implemented using the CERN ROOT analysis framework. ROOT's built-in file-writing tools are used to save the data as .root files. These ROOT files are binary and are designed to prioritize easy retrieval of information while maintaining a compact file size. They use a hierarchical structure for data organization, with data stored in tree-like structures that help track complex systems. The file consists of three parts: header, body, and footer. Each part contains a data tree (TTree), and each tree can hold multiple events. In practice, the header and footer typically contain a single event [5].
- Header:** The header's primary purpose is to define the parameters by which the DAQ was conducted. Parameters include: sampling frequency, readout speed, trigger type, trigger polarity, etc.
- Data:** The body of the file contains 'events' - data from a detected cosmic event. The data recorded notes the size of a given event and data from each individual channel within the DAQ time window. The data is written after each trigger, this is done to reduce data loss in the event of malfunction.
- Footer:** The footer of the file is written at closing the file and contains important information for quality assurance. The footer notes the total number of cosmic events during a physics run across all files.

### ADC-DAQ Software

- A specialized software was developed for the purposes of controlling DT5730 ADC, and data collection [6]. The software was designed to consider the speed, data readability, ADC control function, and real time display (with priority on data collection). The software uses TBB (threading blocks) library to delegate and handle task operation [5, 7].

- The current version of the software offers a real time display where the controls are adjusted, and data can be observed.

### Future Plans

#### Hardware

- Complete construction of Module 3 and 4
- Complete calibration of all modules through various tests
- Analyze data from Module 1 and 2 and start tests such as separation curve

#### Software:

- Adapt new methods for better and more robust ADC-DAQ control.
- Addition of detailed software documentation.
- Development of command-line interface for more dynamic interaction.

#### Command-Line Interface Program:

The current software only allows for the execution of commands through the GUI. The purpose of the new command-line interface (CLI) is to enable the execution of ADC and DAQ controls within a terminal, while maintaining the ability to execute commands through the GUI.

The program will be written in Python 3 and will utilize task queuing as the primary method of task execution. It will run a main control method and use Python's subprocess library to manage ADC-DAQ software execution.

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